

Modbus Register Polymetron 9500 Controller only v2.01

Polymetron 9500 Controller only v2.01

| Name | Register | Data Type | Length | Access Mode | Discrete Range | Min / Max | Description |
|----------------------------------|----------|------------------|--------|-------------|----------------|-----------------|---|
| Calculated Value | 40001 | Float | 2 | R | | | A measurement calculated from sensor measurements |
| Language | 40003 | Selection List | 1 | R/W | ? | | Language to be used on the controller (0=English) |
| Data Format | 40004 | Selection List | 1 | R/W | ? | | Format used for the Data |
| Error Hold Mode | 40005 | Unsigned Integer | 1 | R/W | | 0 /5 | Hold mode when an error occurs |
| Location String | 40006 | String | 8 | R/W | | | Location name for the controller |
| Display Contrast | 40014 | Unsigned Integer | 1 | R/W | | 0 /10 | Display contrast setting (1-9) |
| Calculation Log Mode | 40015 | Unsigned Integer | 1 | R/W | | 0 /3 | Calculated measurement logging mode (0=Snapshot) |
| Calculation Log Interval | 40016 | Unsigned Integer | 1 | R/W | | 0 /7 | Calculated measurement logging mode (0=5sec) |
| Variable X Device Selection | 40017 | Unsigned Integer | 1 | R/W | | 0 /1 | Device selection to be used for the X variable in the calculations (0=Device 1) |
| Variable Y Device Selection | 40018 | Unsigned Integer | 1 | R/W | | 0 /1 | Device selection to be used for the Y variable in the calculations (0=Device 1) |
| Variable X Measurement Selection | 40019 | Unsigned Integer | 1 | R/W | | 0 /15 | Measurement selection to be used for the X variable in the calculations |
| Variable Y Measurement Selection | 40020 | Unsigned Integer | 1 | R/W | | 0 /16 | Measurement selection to be used for the Y variable in the calculations |
| Math Formula | 40021 | Unsigned Integer | 1 | R/W | | 0 /16 | Selection of the math formula used in the calculation |
| Units | 40022 | String | 3 | R/W | | | Units for the calculated value |
| Display Format | 40025 | Unsigned Integer | 1 | R/W | | 0 /16 | Display format for the calculated value |
| Parameter | 40026 | String | 3 | R/W | | | Parameter for the calculated value |
| Auto Range Selection X | 40029 | Unsigned Integer | 1 | R/W | | 0 /15 | Selection of which range (of auto range) measurement to use for variable X |
| Auto Range Selection Y | 40030 | Unsigned Integer | 1 | R/W | | 0 /16 | Selection of which range (of auto range) measurement to use for variable Y |
| Mode | 40031 | Unsigned Integer | 1 | R/W | | 0 /0 | Data logging mode |
| Interval | 40032 | Unsigned Integer | 1 | R/W | | 0 /0 | Data logging interval |
| Source | 40033 | Unsigned Integer | 1 | R/W | | 0 /4 | The source to use for this output (none or probe) |
| Sensor Select | 40034 | Unsigned Integer | 1 | R/W | | 0 /1 | The device to use for this output |
| Measurement Select | 40035 | Unsigned Integer | 1 | R/W | | 0 /15 | The measurement within the sensor for this output |
| Function Select | 40036 | Unsigned Integer | 1 | R/W | | 0 /1 | The output type (0=Linear) |
| Transfer Value | 40037 | Float | 2 | R/W | | 0 /25 | The output value to be used for the transfer setting |
| Filter | 40039 | Unsigned Integer | 1 | R/W | | 0 /999 | Filter time (sec) |
| Zero Select | 40040 | Unsigned Integer | 1 | R/W | | 0 /1 | Selection of the zero level (0=0mA) |
| Minimum Setting | 40041 | Float | 2 | R/W | | -999999 /999999 | The measurement value for the minimum output |
| Maximum Setting | 40043 | Float | 2 | R/W | | -999999 /999999 | The measurement value for the maximum output |
| Knee Value Setting | 40045 | Float | 2 | R/W | | -999999 /999999 | The measurement value for the knee point output |

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| Name | Register | Data Type | Length | Access Mode | Discrete Range | Min / Max | Description |
|----------------------|----------|------------------|--------|-------------|----------------|-----------------|---|
| Knee Current Setting | 40047 | Float | 2 | R/W | | 0 /100.0 | The current value for the knee point output |
| 50 Percent Setting | 40049 | Float | 2 | R/W | | .0001 /999999 | The measurement value for 50% output |
| Mode | 40051 | Unsigned Integer | 1 | R/W | | 0 /1 | The PID mode (0=Auto |
| Manual Setting | 40052 | Float | 2 | R/W | | 0 /100.0 | The manual setting for the output (0 to 100%) |
| Setpoint | 40054 | Float | 2 | R/W | | -999999 /999999 | Setpoint for the PID control |
| Phase | 40056 | Unsigned Integer | 1 | R/W | | 0 /1 | PID phase (0=Direct |
| Proportional Band | 40057 | Float | 2 | R/W | | -999999 /999999 | Propotional Band |
| Integral Time | 40059 | Unsigned Integer | 1 | R/W | | 0 /9999 | Integral Time (0 to 9999 sec) |
| Derivative Time | 40060 | Unsigned Integer | 1 | R/W | | 0 /9999 | Derivative Time (0 to 9999 sec) |
| Transit Time | 40061 | Unsigned Integer | 1 | R/W | | 0 /9999 | Transist Time (0 to 9999 sec) |
| Auto Range Selection | 40062 | Unsigned Integer | 1 | R/W | | 0 /16 | Selection of which range (of auto range) measurement to use |
| Source | 40063 | Unsigned Integer | 1 | R/W | | 0 /4 | The source to use for this output (none or probe) |
| Sensor Select | 40064 | Unsigned Integer | 1 | R/W | | 0 /1 | The device to use for this output |
| Measurement Select | 40065 | Unsigned Integer | 1 | R/W | | 0 /15 | The measurement within the sensor for this output |
| Function Select | 40066 | Unsigned Integer | 1 | R/W | | 0 /3 | The output type (0=Linear |
| Transfer Value | 40067 | Float | 2 | R/W | | 0 /25 | The output value to be used for the transfer setting |
| Filter | 40069 | Unsigned Integer | 1 | R/W | | 0 /999 | Filter time (sec) |
| Zero Select | 40070 | Unsigned Integer | 1 | R/W | | 0 /1 | Selection of the zero level (0=0mA |
| Minimum Setting | 40071 | Float | 2 | R/W | | -999999 /999999 | The measurement value for the minimum output |
| Maximum Setting | 40073 | Float | 2 | R/W | | -999999 /999999 | The measurement value for the maximum output |
| Knee Value Setting | 40075 | Float | 2 | R/W | | -999999 /999999 | The measurement value for the knee point output |
| Knee Current Setting | 40077 | Float | 2 | R/W | | 0 /100.0 | The current value for the knee point output |
| 50 Percent Setting | 40079 | Float | 2 | R/W | | .0001 /999999 | The measurement value for 50% output |
| Mode | 40081 | Unsigned Integer | 1 | R/W | | 0 /1 | The PID mode (0=Auto |
| Manual Setting | 40082 | Float | 2 | R/W | | 0 /100.0 | The manual setting for the output (0 to 100%) |
| Setpoint | 40084 | Float | 2 | R/W | | -999999 /999999 | Setpoint for the PID control |
| Phase | 40086 | Unsigned Integer | 1 | R/W | | 0 /1 | PID phase (0=Direct |
| Proportional Band | 40087 | Float | 2 | R/W | | -999999 /999999 | Propotional Band |
| Integral Time | 40089 | Unsigned Integer | 1 | R/W | | 0 /9999 | Integral Time (0 to 9999 sec) |
| Derivative Time | 40090 | Unsigned Integer | 1 | R/W | | 0 /9999 | Derivative Time (0 to 9999 sec) |
| Transit Time | 40091 | Unsigned Integer | 1 | R/W | | 0 /9999 | Transist Time (0 to 9999 sec) |
| Auto Range Selection | 40092 | Unsigned Integer | 1 | R/W | | 0 /15 | Selection of which range (of auto range) measurement to use |

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| Name | Register | Data Type | Length | Access Mode | Discrete Range | Min / Max | Description |
|----------------------|----------|------------------|--------|-------------|----------------|------------------|--|
| Source | 40093 | Unsigned Integer | 1 | R/W | | 0 / 4 | The source to use for this relay (none |
| Sensor Select | 40094 | Unsigned Integer | 1 | R/W | | 0 / 1 | The device to use for this relay |
| Measurement Select | 40095 | Unsigned Integer | 1 | R/W | | 0 / 15 | The measurement within the sensor for this relay |
| Function Select | 40096 | Unsigned Integer | 1 | R/W | | 0 / 7 | The relay type (0=Alarm |
| Transfer Value | 40097 | Unsigned Integer | 1 | R/W | | 0 / 1 | The relay state to be used for the transfer setting (0=off |
| High Alarm | 40098 | Float | 2 | R/W | | -999999 / 999999 | The high alarm setting |
| Low Alarm | 40100 | Float | 2 | R/W | | -999999 / 999999 | The low alarm setting |
| High Alarm Deadband | 40102 | Float | 2 | R/W | | -999999 / 999999 | The high alarm deadband setting |
| Low Alarm Deadband | 40104 | Float | 2 | R/W | | -999999 / 999999 | The low alarm deadband setting |
| On Delay | 40106 | Unsigned Integer | 1 | R/W | | 0 / 999 | The alarm on delay time (0 to 999 sec) |
| Off Delay | 40107 | Unsigned Integer | 1 | R/W | | 0 / 999 | The alarm off delay time (0 to 999 sec) |
| Setpoint | 40108 | Float | 2 | R/W | | -999999 / 999999 | The relay control setpoint |
| Phase | 40110 | Unsigned Integer | 1 | R/W | | 0 / 1 | The controller action (0=direct |
| Deadband | 40111 | Float | 2 | R/W | | -999999 / 999999 | The controller deadband |
| Overfeed Timer | 40113 | Unsigned Integer | 1 | R/W | | 0 / 999 | The overfeed timer setting (0 to 999 sec) |
| On Delay | 40114 | Unsigned Integer | 1 | R/W | | 0 / 999 | The controller on delay time (0 to 999 sec) |
| Off Delay | 40115 | Unsigned Integer | 1 | R/W | | 0 / 999 | The controller off delay time (0 to 999 sec) |
| Overfeed Timer Reset | 40116 | Unsigned Integer | 1 | R/W | | 0 / 1 | A write resets the overfeed timer |
| Setpoint | 40117 | Float | 2 | R/W | | -999999 / 999999 | The event setpoint |
| Phase | 40119 | Unsigned Integer | 1 | R/W | | 0 / 1 | The event action (0=direct |
| Deadband | 40120 | Float | 2 | R/W | | -999999 / 999999 | The controller deadband |
| Max On Time | 40122 | Unsigned Integer | 1 | R/W | | 0 / 9999 | The event control max on time |
| Min On Time | 40123 | Unsigned Integer | 1 | R/W | | 0 / 9999 | The event control min on time |
| Max Off Time | 40124 | Unsigned Integer | 1 | R/W | | 0 / 9999 | The event control max off time |
| Min Off Time | 40125 | Unsigned Integer | 1 | R/W | | 0 / 9999 | The event control min off time |
| Sensor Hold Type | 40126 | Unsigned Integer | 1 | R/W | | 0 / 0 | Selects the sensor hold type (0=None |
| Sensor Hold Select | 40127 | Unsigned Integer | 1 | R/W | | 0 / 0 | Select probes to hold when this relay is on when the Hold Type is set for particular sensor. (0=sensor 1 |
| Hold Mode | 40128 | Unsigned Integer | 1 | R/W | | 0 / 0 | Selects the hold mode used (1=hold |
| Duration | 40129 | Unsigned Integer | 1 | R/W | | 0 / 0 | Relay on time |

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| Name | Register | Data Type | Length | Access Mode | Discrete Range | Min / Max | Description |
|----------------------|----------|------------------|--------|-------------|----------------|---------------------|---|
| Interval Time | 40130 | Unsigned Integer | 1 | R/W | | 0 / 0 | The interval time between triggering the relay on |
| Off Delay | 40131 | Unsigned Integer | 1 | R/W | | 0 / 0 | The alarm off delay time (0 to 999 sec) |
| Warning Level | 40132 | Unsigned Integer | 1 | R/W | | 0 / 0 | The warning level that triggers the relay |
| Mode | 40133 | Unsigned Integer | 1 | R/W | | 0 / 1 | Manual vs Auto select (0=auto |
| Manual Setting | 40134 | Float | 2 | R/W | | | The manual setting for the output (0 to 100%) |
| Integral Time | 40136 | Unsigned Integer | 1 | R/W | | 0 / 65535 | Integral Time (0 to 9999 sec) |
| Period | 40137 | Float | 2 | R/W | | 0 / 3.40282347 E+38 | Period for PWM control |
| Min Pulse Width | 40139 | Float | 2 | R/W | | 0 / 3.40282347 E+38 | Minimum pulse width |
| Max Pluse Width | 40141 | Float | 2 | R/W | | 0 / 3.40282347 E+38 | Maximum pulse width |
| Range | 40143 | Unsigned Integer | 1 | R/W | | 0 / 16 | Range selection for auto range tags |
| Fail Safe Mode | 40144 | Unsigned Integer | 1 | R/W | | 0 / 16 | Fail Safe Mode (0= off |
| Start Time | 40145 | Time | 2 | R/W | | | Start time for the scheduler |
| Run days | 40147 | Unsigned Integer | 1 | R/W | | 0 / 16 | Run day selection |
| Source | 40148 | Unsigned Integer | 1 | R/W | | 0 / 4 | The source to use for this relay (none |
| Sensor Select | 40149 | Unsigned Integer | 1 | R/W | | 0 / 4 | The device to use for this relay |
| Measurement Select | 40150 | Unsigned Integer | 1 | R/W | | 0 / 15 | The measurement within the sensor for this relay |
| Function select | 40151 | Unsigned Integer | 1 | R/W | | 0 / 0 | The relay type (0=Alarm |
| Transfer Value | 40152 | Unsigned Integer | 1 | R/W | | 0 / 0 | The relay state to be used for the transfer setting |
| High Alarm | 40153 | Float | 2 | R/W | | 0 / 0 | The high alarm setting |
| Low Alarm | 40155 | Float | 2 | R/W | | 0 / 0 | The low alarm setting |
| High Alarm Deadband | 40157 | Float | 2 | R/W | | 0 / 0 | The high alarm deadband setting |
| Low Alarm Deadband | 40159 | Float | 2 | R/W | | 0 / 0 | The low alarm deadband setting |
| On Delay | 40161 | Unsigned Integer | 1 | R/W | | 0 / 0 | The alarm on delay time (0 to 999 sec) |
| Off Delay | 40162 | Unsigned Integer | 1 | R/W | | 0 / 0 | The alarm off delay time (0 to 999 sec) |
| Setpoint | 40163 | Float | 2 | R/W | | 0 / 0 | The relay control setpoint |
| Phase | 40165 | Unsigned Integer | 1 | R/W | | 0 / 0 | The controller action (0=direct |
| Deadband | 40166 | Float | 2 | R/W | | 0 / 0 | The controller deadband |
| Overfeed Timer | 40168 | Unsigned Integer | 1 | R/W | | 0 / 0 | The overfeed timer setting (0 to 999 sec) |
| On Delay | 40169 | Unsigned Integer | 1 | R/W | | 0 / 0 | The controller on delay time (0 to 999 sec) |
| Off Delay | 40170 | Unsigned Integer | 1 | R/W | | 0 / 0 | The controller off delay time (0 to 999 sec) |
| Overfeed Timer Reset | 40171 | Unsigned Integer | 1 | R/W | | 0 / 0 | A write resets the overfeed timer |

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| Name | Register | Data Type | Length | Access Mode | Discrete Range | Min / Max | Description |
|--------------------|----------|------------------|--------|-------------|----------------|---------------------|--|
| Setpoint | 40172 | Float | 2 | R/W | | 0 / 0 | The event setpoint |
| Phase | 40174 | Unsigned Integer | 1 | R/W | | 0 / 0 | The event action (0=direct |
| Deadband | 40175 | Float | 2 | R/W | | 0 / 0 | The controller deadband |
| Max On Time | 40177 | Unsigned Integer | 1 | R/W | | 0 / 0 | The event control max on time |
| Min On Time | 40178 | Unsigned Integer | 1 | R/W | | 0 / 0 | The event control min on time |
| Max Off Time | 40179 | Unsigned Integer | 1 | R/W | | 0 / 0 | The event control max off time |
| Min Off Time | 40180 | Unsigned Integer | 1 | R/W | | 0 / 0 | The event control min off time |
| Sensor Hold Type | 40181 | Unsigned Integer | 1 | R/W | | 0 / 0 | Selects the sensor hold type (0=None |
| Sensor Hold Select | 40182 | Unsigned Integer | 1 | R/W | | 0 / 0 | Select probes to hold when this relay is on when the Hold Type is set for particular sensor. (0=sensor 1 |
| Hold Mode | 40183 | Unsigned Integer | 1 | R/W | | 0 / 0 | Selects the hold mode used (1=hold |
| Duration | 40184 | Unsigned Integer | 1 | R/W | | 0 / 0 | Relay on time |
| Interval Time | 40185 | Unsigned Integer | 1 | R/W | | 0 / 0 | The interval time between triggering the relay on |
| Off Delay | 40186 | Unsigned Integer | 1 | R/W | | 0 / 0 | The alarm off delay time (0 to 999 sec) |
| Warning Level | 40187 | Unsigned Integer | 1 | R/W | | 0 / 0 | The warning level that triggers the relay |
| Mode | 40188 | Unsigned Integer | 1 | R/W | | 0 / 1 | Manual vs Auto select (0=auto |
| Manual Setting | 40189 | Float | 2 | R/W | | | The manual setting for the output (0 to 100%) |
| Integral Time | 40191 | Unsigned Integer | 1 | R/W | | 0 / 65535 | Integral Time (0 to 9999 sec) |
| Period | 40192 | Float | 2 | R/W | | 0 / 3.40282347 E+38 | Period for PWM control |
| Min Pulse Width | 40194 | Float | 2 | R/W | | 0 / 3.40282347 E+38 | Minimum pulse width |
| Max Pulse Width | 40196 | Float | 2 | R/W | | 0 / 3.40282347 E+38 | Maximum pulse width |
| Range | 40198 | Unsigned Integer | 1 | R/W | | 0 / 16 | Range selection for auto range tags |
| Fail Safe Mode | 40199 | Unsigned Integer | 1 | R/W | | 0 / 16 | Fail Safe Mode (0= off |
| Start Time | 40200 | Time | 2 | R/W | | | Start time for the scheduler |
| Run days | 40202 | Unsigned Integer | 1 | R/W | | 0 / 16 | Run day selection |
| Source | 40203 | Unsigned Integer | 1 | R/W | | 0 / 4 | The source to use for this relay (none |
| Sensor Select | 40204 | Unsigned Integer | 1 | R/W | | 0 / 0 | The device to use for this relay |
| Measurement Select | 40205 | Unsigned Integer | 1 | R/W | | 0 / 15 | The measurement within the sensor for this relay |
| Function select | 40206 | Unsigned Integer | 1 | R/W | | 0 / 0 | The relay type (0=Alarm |
| Transfer Value | 40207 | Unsigned Integer | 1 | R/W | | 0 / 0 | The relay state to be used for the transfer setting |

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|----------------------|----------|------------------|--------|-------------|----------------|---------------------|--|
| High Alarm | 40208 | Float | 2 | R/W | | 0 / 0 | The high alarm setting |
| Low Alarm | 40210 | Float | 2 | R/W | | 0 / 0 | The low alarm setting |
| High Alarm Deadband | 40212 | Float | 2 | R/W | | 0 / 0 | The high alarm deadband setting |
| Low Alarm Deadband | 40214 | Float | 2 | R/W | | 0 / 0 | The low alarm deadband setting |
| On Delay | 40216 | Unsigned Integer | 1 | R/W | | 0 / 0 | The alarm on delay time (0 to 999 sec) |
| Off Delay | 40217 | Unsigned Integer | 1 | R/W | | 0 / 0 | The alarm off delay time (0 to 999 sec) |
| Setpoint | 40218 | Float | 2 | R/W | | 0 / 0 | The relay control setpoint |
| Phase | 40220 | Unsigned Integer | 1 | R/W | | 0 / 0 | The controller action (0=direct |
| Deadband | 40221 | Float | 2 | R/W | | 0 / 0 | The controller deadband |
| Overfeed Timer | 40223 | Unsigned Integer | 1 | R/W | | 0 / 0 | The overfeed timer setting (0 to 999 sec) |
| On Delay | 40224 | Unsigned Integer | 1 | R/W | | 0 / 0 | The controller on delay time (0 to 999 sec) |
| Off Delay | 40225 | Unsigned Integer | 1 | R/W | | 0 / 0 | The controller off delay time (0 to 999 sec) |
| Overfeed Timer Reset | 40226 | Unsigned Integer | 1 | R/W | | 0 / 0 | A write resets the overfeed timer |
| Setpoint | 40227 | Float | 2 | R/W | | 0 / 0 | The event setpoint |
| Phase | 40229 | Unsigned Integer | 1 | R/W | | 0 / 0 | The event action (0=direct |
| Deadband | 40230 | Float | 2 | R/W | | 0 / 0 | The controller deadband |
| Max On Time | 40232 | Unsigned Integer | 1 | R/W | | 0 / 0 | The event control max on time |
| Min On Time | 40233 | Unsigned Integer | 1 | R/W | | 0 / 0 | The event control min on time |
| Max Off Time | 40234 | Unsigned Integer | 1 | R/W | | 0 / 0 | The event control max off time |
| Min Off Time | 40235 | Unsigned Integer | 1 | R/W | | 0 / 0 | The event control min off time |
| Sensor Hold Type | 40236 | Unsigned Integer | 1 | R/W | | 0 / 0 | Selects the sensor hold type (0=None |
| Sensor Hold Select | 40237 | Unsigned Integer | 1 | R/W | | 0 / 0 | Select probes to hold when this relay is on when the Hold Type is set for particular sensor. (0=sensor 1 |
| Hold Mode | 40238 | Unsigned Integer | 1 | R/W | | 0 / 0 | Selects the hold mode used (1=hold |
| Duration | 40239 | Unsigned Integer | 1 | R/W | | 0 / 0 | Relay on time |
| Interval Time | 40240 | Unsigned Integer | 1 | R/W | | 0 / 0 | The interval time between triggering the relay on |
| Off Delay | 40241 | Unsigned Integer | 1 | R/W | | 0 / 0 | The alarm off delay time (0 to 999 sec) |
| Warning Level | 40242 | Unsigned Integer | 1 | R/W | | 0 / 0 | The warning level that triggers the relay |
| Mode | 40243 | Unsigned Integer | 1 | R/W | | 0 / 1 | Manual vs Auto select (0=auto |
| Manual Setting | 40244 | Float | 2 | R/W | | | The manual setting for the output (0 to 100%) |
| Integral Time | 40246 | Unsigned Integer | 1 | R/W | | 0 / 65535 | Integral Time (0 to 9999 sec) |
| Period | 40247 | Float | 2 | R/W | | 0 / 3.40282347 E+38 | Period for PWM control |

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|----------------------|----------|------------------|--------|-------------|----------------|--------------------|---|
| Min Pulse Width | 40249 | Float | 2 | R/W | | 0 /3.40282347 E+38 | Minimum pulse width |
| Max Pluse Width | 40251 | Float | 2 | R/W | | 0 /3.40282347 E+38 | Maximum pulse width |
| Range | 40253 | Unsigned Integer | 1 | R/W | | 0 /16 | Range selection for auto range tags |
| Fail Safe Mode | 40254 | Unsigned Integer | 1 | R/W | | 0 /16 | Fail Safe Mode (0= off |
| Start Time | 40255 | Time | 2 | R/W | | | Start time for the scheduler |
| Run days | 40257 | Unsigned Integer | 1 | R/W | | 0 /16 | Run day selection |
| Source | 40258 | Unsigned Integer | 1 | R/W | | 0 /4 | The source to use for this relay (none |
| Sensor Select | 40259 | Unsigned Integer | 1 | R/W | | 0 /4 | The device to use for this relay |
| Measurement Select | 40260 | Unsigned Integer | 1 | R/W | | 0 /15 | The measurement within the sensor for this relay |
| Function select | 40261 | Unsigned Integer | 1 | R/W | | 0 /0 | The relay type (0=Alarm |
| Transfer Value | 40262 | Unsigned Integer | 1 | R/W | | 0 /0 | The relay state to be used for the transfer setting |
| High Alarm | 40263 | Float | 2 | R/W | | 0 /0 | The high alarm setting |
| Low Alarm | 40265 | Float | 2 | R/W | | 0 /0 | The low alarm setting |
| High Alarm Deadband | 40267 | Float | 2 | R/W | | 0 /0 | The high alarm deadband setting |
| Low Alarm Deadband | 40269 | Float | 2 | R/W | | 0 /0 | The low alarm deadband setting |
| On Delay | 40271 | Unsigned Integer | 1 | R/W | | 0 /0 | The alarm on delay time (0 to 999 sec) |
| Off Delay | 40272 | Unsigned Integer | 1 | R/W | | 0 /0 | The alarm off delay time (0 to 999 sec) |
| Setpoint | 40273 | Float | 2 | R/W | | 0 /0 | The relay control setpoint |
| Deadband | 40275 | Float | 2 | R/W | | 0 /0 | The controller deadband |
| Overfeed Timer | 40277 | Unsigned Integer | 1 | R/W | | 0 /0 | The overfeed timer setting (0 to 999 sec) |
| On Delay | 40278 | Unsigned Integer | 1 | R/W | | 0 /0 | The controller on delay time (0 to 999 sec) |
| Off Delay | 40279 | Unsigned Integer | 1 | R/W | | 0 /0 | The controller off delay time (0 to 999 sec) |
| Phase | 40280 | Unsigned Integer | 1 | R/W | | 0 /0 | The controller action (0=direct |
| Overfeed Timer Reset | 40281 | Unsigned Integer | 1 | R/W | | 0 /0 | A write resets the overfeed timer |
| Setpoint | 40282 | Float | 2 | R/W | | 0 /0 | The event setpoint |
| Phase | 40284 | Unsigned Integer | 1 | R/W | | 0 /0 | The event action (0=direct |
| Deadband | 40285 | Float | 2 | R/W | | 0 /0 | The controller deadband |
| Max On Time | 40287 | Unsigned Integer | 1 | R/W | | 0 /0 | The event control max on time |
| Min On Time | 40288 | Unsigned Integer | 1 | R/W | | 0 /0 | The event control min on time |
| Max Off Time | 40289 | Unsigned Integer | 1 | R/W | | 0 /0 | The event control max off time |
| Min Off Time | 40290 | Unsigned Integer | 1 | R/W | | 0 /0 | The event control min off time |
| Sensor Hold Type | 40291 | Unsigned Integer | 1 | R/W | | 0 /0 | Selects the sensor hold type (0=None |

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|----------------------|----------|------------------|--------|-------------|----------------|---------------------|---|
| Sensor Hold Select | 40292 | Unsigned Integer | 1 | R/W | | 0 / 0 | Select probes to hold when this relay is on when the Hold Type is set for particular sensor. (0=sensor 1) |
| Hold Mode | 40293 | Unsigned Integer | 1 | R/W | | 0 / 0 | Selects the hold mode used (1=hold) |
| Duration | 40294 | Unsigned Integer | 1 | R/W | | 0 / 0 | Relay on time |
| Interval Time | 40295 | Unsigned Integer | 1 | R/W | | 0 / 0 | The interval time between triggering the relay on |
| Off Delay | 40296 | Unsigned Integer | 1 | R/W | | 0 / 0 | The alarm off delay time (0 to 999 sec) |
| Warning Level | 40297 | Unsigned Integer | 1 | R/W | | 0 / 0 | The warning level that triggers the relay |
| Mode | 40298 | Unsigned Integer | 1 | R/W | | 0 / 1 | Manual vs Auto select (0=auto) |
| Manual Setting | 40299 | Float | 2 | R/W | | | The manual setting for the output (0 to 100%) |
| Integral Time | 40301 | Unsigned Integer | 1 | R/W | | 0 / 65535 | Integral Time (0 to 9999 sec) |
| Period | 40302 | Float | 2 | R/W | | 0 / 3.40282347 E+38 | Period for PWM control |
| Min Pulse Width | 40304 | Float | 2 | R/W | | 0 / 3.40282347 E+38 | Minimum pulse width |
| Max Pluse Width | 40306 | Float | 2 | R/W | | 0 / 3.40282347 E+38 | Maximum pulse width |
| Range | 40308 | Unsigned Integer | 1 | R/W | | 0 / 16 | Range selection for auto range tags |
| Fail Safe Mode | 40309 | Unsigned Integer | 1 | R/W | | 0 / 16 | Fail Safe Mode (0= off) |
| Start Time | 40310 | Time | 2 | R/W | | | Start time for the scheduler |
| Run days | 40312 | Unsigned Integer | 1 | R/W | | 0 / 16 | Run day selection |
| Discrete 1 Input | 40313 | Unsigned Integer | 1 | R | | 0 / 1 | State of the discrete input #1 |
| Discrete 2 Input | 40314 | Unsigned Integer | 1 | R | | 0 / 1 | State of the discrete input #2 |
| Discrete 3 Input | 40315 | Unsigned Integer | 1 | R | | 0 / 1 | State of the discrete input #3 |
| Smart Sensor 1 Power | 40316 | Unsigned Integer | 1 | R/W | | 0 / 1 | Smart Sensor 1 Power State (0=Off) |
| Smart Sensor 2 Power | 40317 | Unsigned Integer | 1 | R/W | | 0 / 1 | Smart Sensor 2 Power State (0=Off) |
| DM STK LEFT | 40318 | Unsigned Integer | 1 | R | | 0 / 65535 | Device Manager Stack Entries Left |
| SCAN1 STK LEFT | 40319 | Unsigned Integer | 1 | R | | 0 / 65535 | Scan 1 Stack Entries Left |
| SCAN2 STK LEFT | 40320 | Unsigned Integer | 1 | R | | 0 / 65535 | Scan 2 Stack Entries Left |
| SCAN3 STK LEFT | 40321 | Unsigned Integer | 1 | R | | 0 / 65535 | Scan 3 Stack Entries Left |
| SCAN4 STK LEFT | 40322 | Unsigned Integer | 1 | R | | 0 / 65535 | Scan 4 Stack Entries Left |
| SCAN5 STK LEFT | 40323 | Unsigned Integer | 1 | R | | 0 / 65535 | Scan 5 Stack Entries Left |
| MT STK LEFT | 40324 | Unsigned Integer | 1 | R | | 0 / 65535 | Maintance Stack Entries Left |

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| Name | Register | Data Type | Length | Access Mode | Discrete Range | Min / Max | Description |
|----------------------------|----------|------------------|--------|-------------|----------------|---------------|--|
| MB NET STK LFT | 40325 | Unsigned Integer | 1 | R | | 0 /65535 | Modbus Net Stack Entries Left |
| MB AUX STK LFT | 40326 | Unsigned Integer | 1 | R | | 0 /65535 | Modbus Aux Stack Entries Left |
| UI STK LEFT | 40327 | Unsigned Integer | 1 | R | | 0 /65535 | UI Stack Entries Left |
| SYS STK LEFT | 40328 | Unsigned Integer | 1 | R | | 0 /65535 | System Stack Entries Left |
| SD STK LEFT | 40329 | Unsigned Integer | 1 | R | | 0 /65535 | SD card Stack Entries Left |
| Idle time | 40330 | Unsigned Integer | 1 | R | | 0 /65535 | Microprocessor idle time (x100) |
| Clear Stats Count | 40331 | Unsigned Integer | 1 | R/W | | 0 /1 | Clear the Modbus port stats count |
| NetCard Good Msg | 40332 | Unsigned Integer | 2 | R | | 0 /4294967295 | Number of good messages on the Network Card port |
| NetCard Bad Msg | 40334 | Unsigned Integer | 2 | R | | 0 /4294967295 | Number of bad messages on the Network Card port |
| NetCard % Good | 40336 | Float | 2 | R | | 0 /100.0 | Percentage of good messages on the Network Card port |
| Service Port Good Msg | 40338 | Unsigned Integer | 2 | R | | 0 /4294967295 | Number of good messages on the Service port |
| Service Port Bad Msg | 40340 | Unsigned Integer | 2 | R | | 0 /4294967295 | Number of bad messages on the Service port |
| Service Port % Good | 40342 | Float | 2 | R | | 0 /100.0 | Percentage of good messages on the Service Port |
| Port1 Good Msg | 40344 | Unsigned Integer | 2 | R | | 0 /4294967295 | Number of good messages on the Sensor port 1 |
| Port1 Bad Msg | 40346 | Unsigned Integer | 2 | R | | 0 /4294967295 | Number of bad messages on the Port1 |
| Port1 % Good | 40348 | Float | 2 | R | | 0 /100.0 | Percentage of good messages on the Port1 |
| Port2 Good Msg | 40350 | Unsigned Integer | 2 | R | | 0 /4294967295 | Number of good messages on the Sensor port 2 |
| Port2 Bad Msg | 40352 | Unsigned Integer | 2 | R | | 0 /4294967295 | Number of bad messages on the Port2 |
| Port2 % Good | 40354 | Float | 2 | R | | 0 /100.0 | Percentage of good messages on the Port2 |
| Port3 Good Msg | 40356 | Unsigned Integer | 2 | R | | 0 /4294967295 | Number of good messages on the Sensor port 3 |
| Port3 Bad Msg | 40358 | Unsigned Integer | 2 | R | | 0 /4294967295 | Number of bad messages on the Port3 |
| Port3 % Good | 40360 | Float | 2 | R | | 0 /100.0 | Percentage of good messages on the Port3 |
| Port4 Good Msg | 40362 | Unsigned Integer | 2 | R | | 0 /4294967295 | Number of good messages on the Sensor port 4 |
| Port4 Bad Msg | 40364 | Unsigned Integer | 2 | R | | 0 /4294967295 | Number of bad messages on the Port4 |
| Port4 % Good | 40366 | Float | 2 | R | | 0 /100.0 | Percentage of good messages on the Port4 |
| Output 1 Cal Count - 4 mA | 40368 | Unsigned Integer | 1 | R/W | | 0 /25000 | Calibration count for output 1 - 4mA value |
| Output 1 Cal Count - 20 mA | 40369 | Unsigned Integer | 1 | R/W | | 35000 /65533 | Calibration count for output 1 - 20mA value |
| Output 2 Cal Count - 4 mA | 40370 | Unsigned Integer | 1 | R/W | | 0 /25000 | Calibration count for output 2 - 4mA value |
| Output 2 Cal Count - 20 mA | 40371 | Unsigned Integer | 1 | R/W | | 35000 /65533 | Calibration count for output 2 - 20mA value |
| Clear Event Log | 40372 | Unsigned Integer | 1 | R/W | | 1 /4 | Clears one of the device event logs (1=Sensor1) |
| Clear Data Log | 40373 | Unsigned Integer | 1 | R/W | | 1 /4 | Clears one of the device data logs (1=Sensor1) |

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| Name | Register | Data Type | Length | Access Mode | Discrete Range | Min / Max | Description |
|----------------------|----------|------------------|--------|-------------|----------------|--------------|---|
| Output 1 Test Enable | 40374 | Unsigned Integer | 1 | R/W | | 0 /1 | Enable Output 1 Test mode (0=Disabled) |
| Output 1 Value | 40375 | Float | 2 | R/W | | 0 /25.0 | Output 1 Value |
| Output 2 Test Enable | 40377 | Unsigned Integer | 1 | R/W | | 0 /1 | Enable Output 2 Test mode (0=Disabled) |
| Output 2 Value | 40378 | Float | 2 | R/W | | 0 /25.0 | Output 2 Value |
| Relay 1 Test Enable | 40380 | Unsigned Integer | 1 | R/W | | 0 /1 | Enable Relay 1 Test mode (0=Disabled) |
| Relay 1 Value | 40381 | Unsigned Integer | 1 | R/W | | 0 /1 | Relay 1 Value |
| Relay 2 Test Enable | 40382 | Unsigned Integer | 1 | R/W | | 0 /1 | Enable Relay 2 Test mode (0=Disabled) |
| Relay 2 Value | 40383 | Unsigned Integer | 1 | R/W | | 0 /1 | Relay 2 Value |
| Relay 3 Test Enable | 40384 | Unsigned Integer | 1 | R/W | | 0 /1 | Enable Relay 3 Test mode (0=Disabled) |
| Relay 3 Value | 40385 | Unsigned Integer | 1 | R/W | | 0 /1 | Relay 3 Value |
| Relay 4 Test Enable | 40386 | Unsigned Integer | 1 | R/W | | 0 /1 | Enable Relay 4 Test mode (0=Disabled) |
| Relay 4 Value | 40387 | Unsigned Integer | 1 | R/W | | 0 /1 | Relay 4 Value |
| Keyboard Test | 40388 | Unsigned Integer | 1 | R/W | | 0 /0 | Enter key stroke or see last key entry |
| Internal Temperature | 40389 | Float | 2 | R | | -60.0 /190.0 | Internal temperature of the unit |
| 12V Supply | 40391 | Float | 2 | R | | 0 /15.0 | Current 12V supply measurement |
| 3.3V CURRENT | 40393 | Float | 2 | R | | 0 /1.0 | Total 3.3V Supply current (A) |
| 12V CURRENT | 40395 | Float | 2 | R | | 0 /2.51 | Total 12V Supply current (A) |
| SMART SENSOR 1 CUR | 40397 | Float | 2 | R | | 0 /2.5 | Smart Sensor 1 - 12V Supply current (A) |
| SMART SENSOR 2 CUR | 40399 | Float | 2 | R | | 0 /2.5 | Smart Sensor 2 - 12V Supply current (A) |
| ANALOG SENSOR 1 CUR | 40401 | Float | 2 | R | | 0 /0.25 | Analog Sensor 1 - 12V Supply current (A) |
| ANALOG SENSOR 2 CUR | 40403 | Float | 2 | R | | 0 /0.25 | Analog Sensor 2 - 12V Supply current (A) |
| PID 1 Prop Component | 40405 | Float | 2 | R | | 0 /0 | The proportional component of PID1 output |
| PID 1 Intg Component | 40407 | Float | 2 | R | | 0 /0 | The intg component of PID1 output |
| PID 1 Derv Component | 40409 | Float | 2 | R | | 0 /0 | The derv component of PID1 output |
| PID 1 Total | 40411 | Float | 2 | R | | 0 /0 | The total of all component of PID1 output |
| Max Temperature | 40413 | Float | 2 | R | | -60.0 /190.0 | Daily max temperature |
| Min Temperature | 40415 | Float | 2 | R | | -60.0 /190.0 | Daily min temperature |
| LanguageSelected | 40417 | Unsigned Integer | 1 | R/W | | 0 /1 | |
| SecurityEnabled | 40418 | Unsigned Integer | 1 | R/W | | 0 /1 | |
| Password | 40419 | String | 3 | R/W | | | |
| SdCardInstalled | 40422 | Unsigned Integer | 1 | R | | 0 /1 | |
| ErrorCode | 40423 | Unsigned Integer | 1 | R | | 0 /65535 | |
| SerNumString | 40424 | String | 6 | R | | | |
| NONE | 40430 | Unsigned Integer | 1 | R | | 0 /65535 | |
| RESERVED | 40431 | Unsigned Integer | 1 | R | | 0 /65535 | |

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| Name | Register | Data Type | Length | Access Mode | Discrete Range | Min / Max | Description |
|---------------------|----------|------------------|--------|-------------|----------------|---------------|--|
| Network Error | 40432 | Unsigned Integer | 1 | R | | 0 /65535 | Error word for the network (bit0 = Sensor1 communications error) |
| Network Status | 40433 | Unsigned Integer | 1 | R | | 0 /65535 | Status word for the network (bit0 = Sensor1 connected) |
| Sd Board Status | 40434 | Unsigned Integer | 1 | R | | 0 /65535 | |
| SoftwareResetData | 40435 | Unsigned Integer | 2 | R | | 0 /4294967295 | |
| 12V Gound | 40437 | Float | 2 | R | | 0 /2.50 | Current 12V ground measurement |
| FileSelect | 40439 | Unsigned Integer | 1 | R/W | | 0 /8 | |
| FileNumUpdates | 40440 | Unsigned Integer | 1 | R | | 0 /65535 | |
| NetCardAddrMap | 40441 | Unsigned Integer | 1 | R | | 0 /65535 | |
| Set Defaults | 40442 | Unsigned Integer | 1 | R/W | | 0 /1 | Sets the configurations settings to default conditions |
| Initialization Flag | 40443 | Unsigned Integer | 1 | R/W | | 0 /1 | This flag is set after the input has been initialized |
| Initialization Flag | 40444 | Unsigned Integer | 1 | R/W | | 0 /1 | This flag is set after the input has been initialized |
| Initialization Flag | 40445 | Unsigned Integer | 1 | R/W | | 0 /1 | This flag is set after the input has been initialized |
| Mode | 40446 | Unsigned Integer | 1 | R/W | | 0 /2 | Input mode of operation (0=Disabled |
| Mode | 40447 | Unsigned Integer | 1 | R/W | | 0 /2 | Input mode of operation (0=Disabled |
| Mode | 40448 | Unsigned Integer | 1 | R/W | | 0 /2 | Input mode of operation (0=Disabled |
| Warning Enable | 40449 | Unsigned Integer | 1 | R/W | | 0 /1 | Warning enable flag (0=Disabled |
| Warning Enable | 40450 | Unsigned Integer | 1 | R/W | | 0 /1 | Warning enable flag (0=Disabled |
| Warning Enable | 40451 | Unsigned Integer | 1 | R/W | | 0 /1 | Warning enable flag (0=Disabled |
| Hold Mode | 40452 | Unsigned Integer | 1 | R/W | | 0 /2 | Hold Mode (1=Active |
| Hold Mode | 40453 | Unsigned Integer | 1 | R/W | | 0 /2 | Hold Mode (1=Active |
| Hold Mode | 40454 | Unsigned Integer | 1 | R/W | | 0 /2 | Hold Mode (1=Active |
| Hold Selection | 40455 | Unsigned Integer | 1 | R/W | | 0 /3 | Select which sensor use the Hold Mode (bit 0=Sensor 1 |
| Hold Selection | 40456 | Unsigned Integer | 1 | R/W | | 0 /3 | Select which sensor use the Hold Mode (bit 0=Sensor 1 |
| Hold Selection | 40457 | Unsigned Integer | 1 | R/W | | 0 /3 | Select which sensor use the Hold Mode (bit 0=Sensor 1 |
| On Delay | 40458 | Unsigned Integer | 1 | R/W | | 0 /999 | On delay time (sec) |
| On Delay | 40459 | Unsigned Integer | 1 | R/W | | 0 /999 | On delay time (sec) |
| On Delay | 40460 | Unsigned Integer | 1 | R/W | | 0 /999 | On delay time (sec) |
| Off Delay | 40461 | Unsigned Integer | 1 | R/W | | 0 /999 | Off delay time (sec) |
| Off Delay | 40462 | Unsigned Integer | 1 | R/W | | 0 /999 | Off delay time (sec) |

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| Name | Register | Data Type | Length | Access Mode | Discrete Range | Min / Max | Description |
|-----------------------------|----------|------------------|--------|-------------|----------------|---------------|--|
| Off Delay | 40463 | Unsigned Integer | 1 | R/W | | 0 /999 | Off delay time (sec) |
| Slot 0 Mapping | 40464 | Unsigned Integer | 1 | R | | 0 /65535 | Bit field mapping of relay and analog output mapping of the sensor installed in slot 0 |
| Slot 0 Mapping | 40465 | Unsigned Integer | 1 | R | | 0 /65535 | Bit field mapping of relay and analog output mapping of the sensor installed in slot 0 |
| Telegram Configuration Mode | 40466 | Unsigned Integer | 1 | R/W | | 0 /1 | Sets the Profibus Telegram configuration to Auto Mode (0) or Manual Mode (1) |
| AutoTelegram | 40467 | Unsigned Integer | 1 | R/W | | 0 /1 | |
| Relay1WarningLevel | 40468 | Unsigned Integer | 2 | R/W | | 0 /4294967295 | The warning level that triggers the relay |
| Relay2WarningLevel | 40470 | Unsigned Integer | 2 | R/W | | 0 /0 | The warning level that triggers the relay |
| Relay3WarningLevel | 40472 | Unsigned Integer | 2 | R/W | | 0 /0 | The warning level that triggers the relay |
| Relay4WarningLevel | 40474 | Unsigned Integer | 2 | R/W | | 0 /0 | The warning level that triggers the relay |
| ResinWatch | 40476 | Unsigned Integer | 1 | R/W | | 0 /1 | Watch resin life length |
| ResinCapacity | 40477 | Float | 2 | R/W | | 0.5 /5.0 | |
| ResinVolume | 40479 | Float | 2 | R/W | | 0.5 /20.0 | |
| ResinFlow | 40481 | Float | 2 | R/W | | 2.0 /20.0 | |
| ResinConcentration | 40483 | Float | 2 | R/W | | 0.0 /20.0 | |
| ResinInstallationDate | 40485 | Date | 2 | R/W | | | |
| ResinTimeLeft | 40487 | Float | 2 | R | | 0 /999 | |

ALL Sensors and Analyzer: Classified ERROR Word - Register 49930

Table 2 Error register

| Bit | Error | Description |
|-----|----------------------------------|---|
| 0 | Calibration error | Faulty calibration detected |
| 1 | Electronic settings error | Faulty electronic calibration/settings |
| 2 | Cleaning error | Error in cleaning cycle detected |
| 3 | Measuring module error | Error in measuring module detected |
| 4 | System initialization | Inconsistent settings detected, reset to factory settings |
| 5 | Hardware error | Faulty hardware detected |
| 6 | Internal communication error | Internal communication error detected |
| 7 | Humidity error | Excessive humidity detected |
| 8 | Excessive temperature | Excessive temperature detected |
| 9 | | |
| 10 | Sample feed warning | Error in sample feed detected |
| 11 | Questionable calibration warning | Accuracy of previous calibration inadequate |
| 12 | Questionable measurement warning | Accuracy of previous measurement inadequate/out of range |
| 13 | Safety warning | Safety equipment error detected |
| 14 | Reagent warning | Reagent warning, e.g. fill level < min detected |
| 15 | Service request warning | Service request detected |

ALL Sensors and Analyzer: Classified STATUS Word - Register 49931

Table 3 Status register

| Bit | Status 1 | Description |
|-----|---|--|
| 0 | Calibration activated | Calibration in progress, measurement value not up to date |
| 1 | Cleaning activated | Cleaning in progress, measurement value not up to date |
| 2 | Service mode activated | Device in "Service" mode, measurement value not up to date |
| 3 | General error message | General error detected, refer to error text for details |
| 4 | Measurement value channel 0, poor quality | Measurement accuracy is not within specified limits |
| 5 | Measurement value channel 0, range short-fall | Measurement value falls short of the specified range |
| 6 | Measurement value channel 0, range exceeded | Measurement value exceeds the specified range |
| 7 | Measurement value channel 1, poor quality | Measurement accuracy is not within specified limits |
| 8 | Measurement value channel 1, range short-fall | Measurement value falls short of the specified range |
| 9 | Measurement value channel 1, range exceeded | Measurement value exceeds the specified range |
| 10 | Measurement value channel 2, poor quality | Measurement accuracy is not within specified limits |
| 11 | Measurement value channel 2, range short-fall | Measurement value falls short of the specified range |
| 12 | Measurement value channel 2, range exceeded | Measurement value exceeds the specified range |
| 13 | Measurement value channel 3, poor quality | Measurement accuracy is not within specified limits |
| 14 | Measurement value channel 3, range short-fall | Measurement value falls short of the specified range |
| 15 | Measurement value channel 3, range exceeded | Measurement value exceeds the specified range |